

Inclass 06: Linear Regression

[SCS4049] Machine Learning and Data Science

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Linear regression

Linear regression

Linear model

$$\hat{y} = \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \cdots + \theta_n x_n \quad (1)$$

In this equation,

- \hat{y} is the predicted value (for true y)
- n is the number of features
- x_i is the i -th feature value
- θ is the j -th model parameter (including the bias term θ_0 and the feature weights $\theta_1, \theta_2, \dots, \theta_n$)

Linear regression

This can be written much more concisely using a vectorized form,

$$\hat{y} = \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \cdots + \theta_n x_n \quad (2)$$

$$= h_{\theta}(\mathbf{x}) = \boldsymbol{\theta} \cdot \mathbf{x} \quad (3)$$

In this equation,

- $\boldsymbol{\theta}$ is the model's *parameter vector*, containing the bias term θ_0 and the feature weights θ_1 to θ_n
- \mathbf{x} is the instance's *feature vector*, containing x_0 to x_n always equal to 1
- $\boldsymbol{\theta} \cdot \mathbf{x}$ is the dot product of the vectors $\boldsymbol{\theta}$ and \mathbf{x} , which is of course equal to $\theta_0 x_0 + \theta_1 x_1 + \cdots + \theta_n x_n$
- h_{θ} is the hypothesis function, using the model parameter $\boldsymbol{\theta}$

Linear regression

That's the linear regression model – but how do we train it?

Recall that training a model means setting its parameters so that the model best fits the training set.

We first need a measure of how well (or poorly) the model fits the training data.

The most common performance measure of a regression model is the Root Mean Square Error (RMSE).

$$\text{RMSE}(\mathbf{X}, h) = \sqrt{\frac{1}{m} \sum_{i=1}^m (h(\mathbf{x}^{(i)}) - y^{(i)})^2} \quad (4)$$

Linear regression

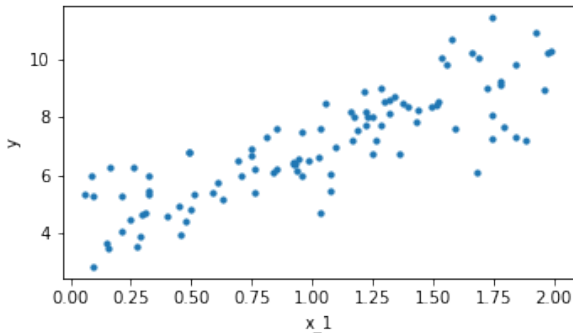


Figure 1: Linear regression: training dataset

Generating training dataset

$$y \approx \theta_0 + \theta_1 x \quad (5)$$

$$y = \theta_0 + \theta_1 x + \epsilon \text{ where } \epsilon \sim \mathcal{N}(0, \sigma^2) \quad (6) \quad 4/21$$

Linear regression: design matrix

Design matrix (regressor matrix, model matrix, data matrix)

- 훈련 데이터(sample, example)이 m 개
- feature vector \mathbf{x} 의 차원이 n 일 때,
- m 개의 sample을 row vector로 한 design matrix \mathbf{X} 로 표시할 수 있음

$$\mathbf{y} = \begin{bmatrix} y^{(1)} \\ y^{(2)} \\ \vdots \\ y^{(m)} \end{bmatrix} \quad \boldsymbol{\theta} = \begin{bmatrix} \theta_1 \\ \theta_2 \\ \vdots \\ \theta_n \end{bmatrix} \quad (7)$$

$$\mathbf{X} = \begin{bmatrix} \text{1st sample } \tilde{\mathbf{x}}^{(1)} \\ \text{2nd sample } \tilde{\mathbf{x}}^{(2)} \\ \dots \\ \text{m-th sample } \tilde{\mathbf{x}}^{(m)} \end{bmatrix} = \begin{bmatrix} \tilde{X}_1^{(1)} & \tilde{X}_2^{(1)} & \dots & \tilde{X}_n^{(1)} \\ \tilde{X}_1^{(2)} & \tilde{X}_2^{(2)} & \dots & \tilde{X}_n^{(2)} \\ \vdots & \vdots & \vdots & \vdots \\ \tilde{X}_1^{(m)} & \tilde{X}_2^{(m)} & \dots & \tilde{X}_n^{(m)} \end{bmatrix} \quad (8)$$

Linear regression: design matrix

그러면, $\hat{y} = \boldsymbol{\theta}^T \mathbf{x}$ 의 m 개의 sample에 대해 다음과 같이 표현할 수 있음

$$\hat{\mathbf{y}} = \mathbf{X}\boldsymbol{\theta} \quad (9)$$

$$\begin{bmatrix} y^{(1)} \\ y^{(2)} \\ \vdots \\ y^{(m)} \end{bmatrix} = \begin{bmatrix} \tilde{x}_1^{(1)} & \tilde{x}_2^{(1)} & \cdots & \tilde{x}_n^{(1)} \\ \tilde{x}_1^{(2)} & \tilde{x}_2^{(2)} & \cdots & \tilde{x}_n^{(2)} \\ \vdots & \vdots & \vdots & \vdots \\ \tilde{x}_1^{(m)} & \tilde{x}_2^{(m)} & \cdots & \tilde{x}_n^{(m)} \end{bmatrix} \begin{bmatrix} \theta_1 \\ \theta_2 \\ \vdots \\ \theta_n \end{bmatrix} \quad (10)$$

$$\begin{bmatrix} y^{(1)} \\ y^{(2)} \\ \vdots \\ y^{(m)} \end{bmatrix} = \begin{bmatrix} \tilde{\mathbf{x}}^{(1)} \\ \tilde{\mathbf{x}}^{(2)} \\ \vdots \\ \tilde{\mathbf{x}}^{(m)} \end{bmatrix} \boldsymbol{\theta} \quad (11)$$

Normal equation: geometric approach

Design matrix \mathbf{X} 의 각 열을 \vec{x}_j 라고 하면

$$\hat{\mathbf{y}} = \mathbf{X}\boldsymbol{\theta} = \begin{bmatrix} \vec{x}_1 & \vec{x}_2 & \cdots & \vec{x}_n \end{bmatrix} \begin{bmatrix} \theta_1 \\ \theta_2 \\ \vdots \\ \theta_n \end{bmatrix} \quad (12)$$

$$= \theta_1 \vec{x}_1 + \theta_2 \vec{x}_2 + \cdots + \theta_n \vec{x}_n \quad (13)$$

즉, $\hat{\mathbf{y}}$ 는 $\vec{x}_1, \vec{x}_2, \dots, \vec{x}_n$ 이 생성하는 hyperplane 상에 존재함

Residual 또는 error의 크기 $\|\mathbf{y} - \hat{\mathbf{y}}\|$ 를 최소화 하려면? 위의 hyperplane과 error $\mathbf{y} - \hat{\mathbf{y}}$ 가 서로 수직(orthogonal)해야함

Normal equation: geometric interpretation

Residual 또는 error의 크기 $\|\mathbf{y} - \hat{\mathbf{y}}\|$ 를 최소화 하려면? 위의 hyperplane과 error $\mathbf{y} - \hat{\mathbf{y}}$ 가 서로 수직(orthogonal)해야함
즉, 모든 column vector에 대해서

$$\vec{\mathbf{x}}_j^T (\mathbf{y} - \hat{\mathbf{y}}) = 0 \quad (14)$$

이 성립해야 함

전체 m 개의 sample에 대해서

$$\mathbf{X}^T (\mathbf{y} - \mathbf{X}\boldsymbol{\theta}) = 0 \quad \implies \quad \mathbf{X}^T \mathbf{X}\boldsymbol{\theta} = \mathbf{X}^T \mathbf{y} \quad (15)$$

$$\hat{\boldsymbol{\theta}} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y} \quad (16)$$

Normal equation: geometric interpretation

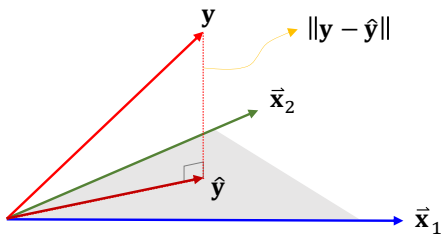


Figure 2: Normal equation: geometric interpretation

Normal equation

$$\hat{\boldsymbol{\theta}} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y} \quad (17)$$

Projection matrix

$$\hat{\mathbf{y}} = \mathbf{X} \hat{\boldsymbol{\theta}} = \mathbf{X} (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y} \quad (18)$$

Normal equation: analytic approach

Sum of squared error (SSE)

$$\text{SSE} = \sum_{i=1}^m (y^{(i)} - \hat{y}^{(i)})^2 \quad (19)$$

$$= \|\mathbf{y} - \hat{\mathbf{y}}\|^2 = (\mathbf{y} - \hat{\mathbf{y}})^T (\mathbf{y} - \hat{\mathbf{y}}) \quad (20)$$

Using $\hat{\mathbf{y}} = \mathbf{X}\boldsymbol{\theta}$

$$\text{SSE}(\boldsymbol{\theta}) = \mathbf{y}^T \mathbf{y} - 2\mathbf{y}^T \mathbf{X}\boldsymbol{\theta} + (\mathbf{X}\boldsymbol{\theta})^T (\mathbf{X}\boldsymbol{\theta}) = \mathbf{y}^T \mathbf{y} - 2\mathbf{y}^T \mathbf{X}\boldsymbol{\theta} + \boldsymbol{\theta}^T \mathbf{X}^T \mathbf{X}\boldsymbol{\theta} \quad (21)$$

$$\frac{\partial \text{SSE}(\boldsymbol{\theta})}{\partial \boldsymbol{\theta}} = 2(\mathbf{X}^T \mathbf{X}\boldsymbol{\theta} - \mathbf{X}^T \mathbf{y}) = 0 \quad \implies \quad \mathbf{X}^T \mathbf{X}\boldsymbol{\theta} = \mathbf{X}^T \mathbf{y} \quad (22)$$

Hence, we have

$$\hat{\boldsymbol{\theta}} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y} \quad (23)$$

$$\hat{\mathbf{y}} = \mathbf{X}(\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y} \quad (24)$$

Linear regression: cost function

We need to find the value of $\boldsymbol{\theta}$ that minimizes the RMSE. In practice, it is simpler to minimize the sum of squared error (SSE) than the MSE or the RMSE.

$$\hat{\boldsymbol{\theta}} = \arg \min \text{RMSE}(\mathbf{X}, h_{\boldsymbol{\theta}}) = \arg \min \sqrt{\frac{1}{m} \sum_{i=1}^m \left(\boldsymbol{\theta}^T \mathbf{x}^{(i)} - y^{(i)} \right)^2} \quad (25)$$

$$= \arg \min \text{MSE}(\mathbf{X}, h_{\boldsymbol{\theta}}) = \arg \min \frac{1}{m} \sum_{i=1}^m \left(\boldsymbol{\theta}^T \mathbf{x}^{(i)} - y^{(i)} \right)^2 \quad (26)$$

$$= \arg \min \text{SSE}(\mathbf{X}, h_{\boldsymbol{\theta}}) = \arg \min \sum_{i=1}^m \left(\boldsymbol{\theta}^T \mathbf{x}^{(i)} - y^{(i)} \right)^2 \quad (27)$$

Linear regression: closed form solution

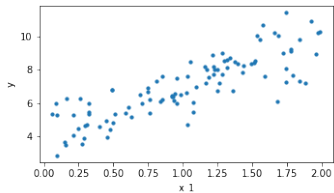


Figure 3: Linear regression: training dataset

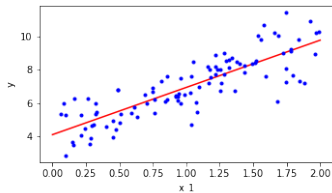


Figure 4: Linear regression: closed form solution

Normal equation의 계산

- Normal equation에 의한 예측치 $\hat{\mathbf{y}}$

$$\hat{\mathbf{y}} = \mathbf{X}(\mathbf{X}^T\mathbf{X})^{-1}\mathbf{X}^T\mathbf{y} \quad (28)$$

- $\mathbf{X} \in \mathcal{R}^{m \times n}$
- $\mathbf{X}^T\mathbf{X} \in \mathcal{R}^{n \times n}$
- $(\mathbf{X}^T\mathbf{X})^{-1}$ 의 계산 복잡도 = $O(n^{2.4}) \sim O(n^3)$
- Feature 수의 약 세제곱으로 계산 시간이 증가

Gradient descent

Batch gradient descent

Linear regression model $\hat{\mathbf{y}} = \mathbf{X}\boldsymbol{\theta}$

$$J(\boldsymbol{\theta}) = \text{SSE}(\boldsymbol{\theta}) = \|\mathbf{y} - \mathbf{X}\boldsymbol{\theta}\|^2 \quad (29)$$

$$\nabla_{\boldsymbol{\theta}} J(\boldsymbol{\theta}) = \frac{\partial}{\partial \boldsymbol{\theta}} J(\boldsymbol{\theta}) = 2\mathbf{X}^T(\mathbf{X}\boldsymbol{\theta} - \mathbf{y}) \quad (30)$$

$$\nabla_{\boldsymbol{\theta}} J(\boldsymbol{\theta}) = \begin{bmatrix} \frac{\partial}{\partial \theta_1} J(\boldsymbol{\theta}) \\ \frac{\partial}{\partial \theta_2} J(\boldsymbol{\theta}) \\ \vdots \\ \frac{\partial}{\partial \theta_n} J(\boldsymbol{\theta}) \end{bmatrix} = \begin{bmatrix} 2 \sum_{i=1}^m x_1^{(i)} \left(\boldsymbol{\theta}^T \mathbf{x}^{(i)} - y^{(i)} \right) \\ 2 \sum_{i=1}^m x_2^{(i)} \left(\boldsymbol{\theta}^T \mathbf{x}^{(i)} - y^{(i)} \right) \\ \vdots \\ 2 \sum_{i=1}^m x_n^{(i)} \left(\boldsymbol{\theta}^T \mathbf{x}^{(i)} - y^{(i)} \right) \end{bmatrix} \quad (31)$$

Gradient descent step

$$\boldsymbol{\theta}^{t+1} = \boldsymbol{\theta}^t - \eta \nabla_{\boldsymbol{\theta}} J(\boldsymbol{\theta}^t) \quad (32)$$

where iteration number t and $\boldsymbol{\theta}$ arbitrary initial value

Batch gradient descent

Batch gradient descent에서

$$\frac{\partial}{\partial \boldsymbol{\theta}} J(\boldsymbol{\theta}) = 2\mathbf{X}^T(\mathbf{X}\boldsymbol{\theta} - \mathbf{y}) \quad (33)$$

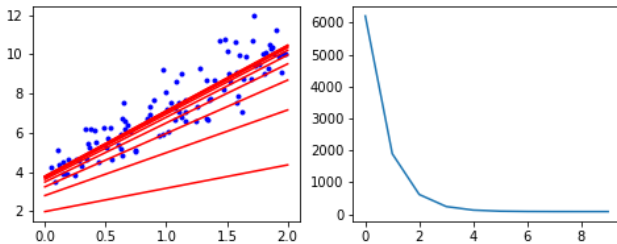
$$= 2 \begin{bmatrix} \mathbf{x}^{(1)} & \mathbf{x}^{(2)} & \dots & \mathbf{x}^{(m)} \end{bmatrix} \begin{bmatrix} \boldsymbol{\theta}^T \mathbf{x}^{(1)} - y^{(1)} \\ \boldsymbol{\theta}^T \mathbf{x}^{(2)} - y^{(2)} \\ \vdots \\ \boldsymbol{\theta}^T \mathbf{x}^{(m)} - y^{(m)} \end{bmatrix} \quad (34)$$

$$= 2 \sum_{i=1}^m \mathbf{x}^{(i)} \left(\boldsymbol{\theta}^T \mathbf{x}^{(i)} - y^{(i)} \right) \quad (35)$$

그러므로 이 gradient vector의 j 번째 component는

$$\frac{\partial}{\partial \theta_j} J(\boldsymbol{\theta}) = 2 \sum_{i=1}^m x_j^{(i)} \left(\boldsymbol{\theta}^T \mathbf{x}^{(i)} - y^{(i)} \right) \quad (36)$$

Batch gradient descent



Batch gradient descent algorithm

- 매 스텝마다 batch 전체에 대한 계산 필요
- 데이터셋이 커지면 속도가 느려짐
- Normal equation: feature 수에 따라 계산 속도가 지수적으로 느려짐
- Gradient descent: feature 수가 늘어도 크게 변하지 않음

Learning rate

- Hyperparameter인 학습률(learning rate) η 가 너무 작은 경우 시간이 오래 걸림
- 너무 큰 경우 최적해를 지나쳐 해를 찾지 못할 수 있음

- Constant learning rate
 - 보통 0.1, 0.01부터 시작하여 여러 가지 값으로 시험해보며 범위를 좁혀 나감
- Time-based decay

$$\eta = \frac{\eta_0}{(1 + kt)} \quad (37)$$

η_0 : 학습률 초기값, k : hyperparameter, t : iteration

- Step decay
 - 정해진 epoch마다 학습률을 줄이는 방법
 - 예: 5 epoch마다 반으로, 20 epoch마다 1/10로
 - Epoch: 훈련 데이터셋 전체를 모두 사용할 때 = 한 epoch
- Exponential decay

$$\eta = \eta_0 e^{-kt} \quad (38)$$

η_0 : 학습률 초기값, k : hyperparameter, t : iteration

Stochastic gradient descent

For our linear regression model $\hat{y} = \boldsymbol{\theta}^T \mathbf{x}$

$$J(\boldsymbol{\theta}) = \text{SSE}(\boldsymbol{\theta}) = \sum_{i=1}^m \left(\mathbf{y}^{(i)} - \boldsymbol{\theta}^T \mathbf{x}^{(i)} \right)^2 = \sum_{i=1}^m J_i(\boldsymbol{\theta}) \quad (39)$$

$$\boldsymbol{\theta}^{t+1} = \boldsymbol{\theta}^t - 2\eta \left(\mathbf{y}^{(t)} - (\boldsymbol{\theta}^t)^T \mathbf{x}^{(t)} \right) \mathbf{x}^{(t)} \quad (40)$$

- 무작위로 선택한 한 개의 sample에 대해서만 gradient를 계산하여 parameter를 update
- sequential learning or online learning
- 대규모 데이터셋을 처리하는데 유리
- 선택하는 사례의 무작위성으로 움직임이 불규칙
- BGD에 비해 local optimum에서 쉽게 빠져나올 수 있음
- 최적해에 도달하지만 지속적으로 요동
- BGD와 마찬가지로 global optimum이라는 보장이 없음

Mini-batch gradient descent

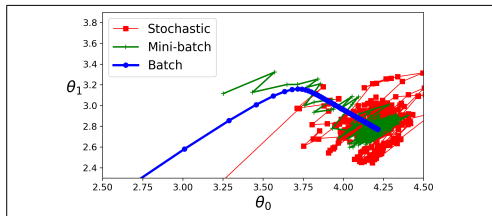


Figure 4-11. Gradient Descent paths in parameter space

- 훈련 데이터셋을 작은 크기의 무작위 부분 집합으로 나누어서 gradient 를 구하는 방법
- 예 100,000개의 데이터 = (mini-batch size 100) × (1,000 mini-batches)
- Batch gradient descent와 stochastic gradient descent(SGD)의 절충
- SGD보다 불규칙한 움직임이 덜함
- SGD보다 local minimum에서 빠져나오기가 상대적으로 더 어려움
- GPU를 통한 매트릭스 연산의 속도를 높일 수 있음

Linear regression comparison

Table 4-1. Comparison of algorithms for Linear Regression

Algorithm	Large m	Out-of-core support	Large n	Hyperparams	Scaling required	Scikit-Learn
Normal Equation	Fast	No	Slow	0	No	n/a
SVD	Fast	No	Slow	0	No	LinearRegression
Batch GD	Slow	No	Fast	2	Yes	SGDRegressor
Stochastic GD	Fast	Yes	Fast	≥ 2	Yes	SGDRegressor
Mini-batch GD	Fast	Yes	Fast	≥ 2	Yes	SGDRegressor



There is almost no difference after training: all these algorithms end up with very similar models and make predictions in exactly the same way.