

# Preclass 08: Dual Problem and KKT conditions

[SCS4049] Machine Learning and Data Science

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standard form problem

$$\text{minimize } f_0(x) \quad (1)$$

$$\text{subject to } f_i(x) \leq 0, \quad i = 1, 2, \dots, m \quad (2)$$

$$h_i(x) = 0, \quad i = 1, 2, \dots, p \quad (3)$$

variable  $x \in \mathcal{R}^n$ , domain  $\mathcal{D}$ , optimal value  $p^*$

Lagrangian:  $L : \mathcal{R}^n \times \mathcal{R}^m \times \mathcal{R}^p \rightarrow \mathcal{R}$  with  $\text{dom } L = \mathcal{D} \times \mathcal{R}^m \times \mathcal{R}^p$

$$L(x, \lambda, \nu) = f_0(x) + \sum_{i=1}^m \lambda_i f_i(x) + \sum_{i=1}^p \nu_i h_i(x) \quad (4)$$

- weighted sum of objective and constraint functions
- $\lambda_i$  is Lagrange multiplier associated with  $f_i(x) \leq 0$
- $\nu_i$  is Lagrange multiplier associated with  $h_i(x) = 0$

# Lagrange dual function

Lagrange dual function:  $g : \mathcal{R}^m \times \mathcal{R}^p \rightarrow \mathcal{R}$

$$g(\lambda, \nu) = \inf_{x \in \mathcal{D}} L(x, \lambda, \nu) \quad (5)$$

$$= \inf_{x \in \mathcal{D}} \left( f_0(x) + \sum_{i=1}^m \lambda_i f_i(x) + \sum_{i=1}^p \nu_i h_i(x) \right) \quad (6)$$

$g$  is concave, can be  $-\infty$  for some  $\lambda, \nu$

lower bound property: if  $\lambda \geq 0$ , then  $g(\lambda, \nu) \leq p^*$

proof: if  $\tilde{x}$  is feasible and  $\lambda \geq 0$ , then

$$f_0(\tilde{x}) \geq L(\tilde{x}, \lambda, \nu) \geq \inf_{x \in \mathcal{D}} L(x, \lambda, \nu) = g(\lambda, \nu) \quad (7)$$

minimizing over all feasible  $\tilde{x}$  gives  $p^* \geq g(\lambda, \nu)$

# The dual problem

Lagrange dual problem

$$\text{maximize } g(\lambda, \nu) \quad (8)$$

$$\text{subject to } \lambda \geq 0 \quad (9)$$

- finds best lower bound on  $p^*$ , obtained from Lagrange dual function
- a convex optimization problem; optimal value denoted  $d^*$
- $\lambda, \nu$  are dual feasible if  $\lambda \geq 0, (\lambda, \nu) \in \text{dom } g$
- often simplified by making implicit constraint  $(\lambda, \nu) \in \text{dom } g$  explicit

# Weak and strong duality

weak duality:  $d^* \leq p^*$

- always holds (for convex and nonconvex problems)
- can be used to find nontrivial lower bounds for difficult problems

strong duality:  $d^* = p^*$

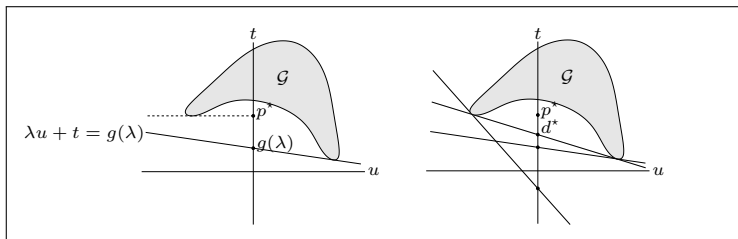
- does not hold in general
- holds for convex problems
- conditions that guarantee strong duality in convex problems are called constraint qualifications

# Geometric interpretation

for simplicity, consider problem with one constraint  $f_1(x) \leq 0$

interpretation of dual function

$$g(\lambda) = \inf_{(u,t) \in \mathcal{G}} (t + \lambda u) \quad \text{where } \mathcal{G} = \{(f_1(x), f_0(x)) \mid x \in \mathcal{D}\} \quad (10)$$



- $\lambda u + t = g(\lambda)$  is supporting hyperplane to  $\mathcal{G}$
- hyperplane intersects  $t$ -axis at  $t = g(\lambda)$

## Karush-Kuhn-Tucker (KKT) conditions

the following four conditions are called KKT conditions (for a problem with differentiable  $f_i, h_i$ )

1. primal constraints:  $f_i(x) \leq 0$   $i = 1, \dots, m$ ,  $h_i(x) = 0$ ,  $i = 1, \dots, p$
2. dual constraints:  $\lambda \geq 0$
3. complementary slackness:  $\lambda_i f_i(x) = 0$ ,  $i = 1, \dots, m$
4. gradient of Lagrangian with respect to  $x$  vanishes:

$$\nabla f_0(x) + \sum_{i=1}^m \lambda_i \nabla f_i(x) + \sum_{i=1}^p \nu_i \nabla h_i(x) = 0 \quad (11)$$

if strong duality holds and  $x, \lambda, \nu$  are optimal, then they must satisfy the KKT conditions

# Appendix

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## Reference and further reading

- “Chap 7 | Sparse Kernel Machines” of C. Bishop, Pattern Recognition and Machine Learning
- “Chap 5 | Support Vector Machines” of A. Geron, Hands-On Machine Learning with Scikit-Learn, Keras & TensorFlow
- “Chap 4 | Convex Optimization Problems”, “Chap 5 | Duality” of S. Boyd, Convex Optimization